

# MIVR Two-axial Three-light micro-pod



## Features

- ✧ The extreme light small, weight  $\leq 325\text{g}$
- ✧ Support for heading full angle range (360) rotation
- ✧ Target tracking and image compression
- ✧ Wide pressure of 12~28V input, dynamic power consumption control
- ✧ With AI pedestrian and vehicle identification function

## Specifications

### System specification

System type	Gyro stability
Weight	$\leq 325\text{g}$

### System characteristics

Platform type	Two-axial
Pitch	$-110^\circ \sim +100^\circ$
Yaw	$n \times 360^\circ$
Max angular velocity	$\geq 100^\circ/\text{s}$
Stability accuracy	$0.1\text{mrad}(1^\circ/2\text{HZ})(1\sigma)$
Motor encoder accuracy	$\leq 0.3^\circ$

### Electro-Optic

Resolution	$1920 \times 1080 @ 60\text{fps}$
FOV	$19^\circ \times 11^\circ$ (16mm)

### Thermal IR

Resolution	$640 \times 512 @ 60\text{fps}$
FOV	$18.1^\circ \times 14.5^\circ$ (24mm)

### Target tracking

Tracking speed	$\geq 40^\circ/\text{s}$
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### Laser Ranging

Measuring	5~1200m
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### System interface

Control interface	RS232/TCP
Video output	network(Rtsp)

### Power supply

Supply voltage	12 ~ 28V
Power consumption	$A_v \leq 10\text{W}$ , $\text{Max} \leq 20\text{W}$

### Environmental conditions

Operating temperature	$-20^\circ\text{C} \sim +60^\circ\text{C}$
Storage temperature	$-50^\circ\text{C} \sim +70^\circ\text{C}$

## Mechanical

